# IRPS Instant Robot Programming System

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Efficient welding of small batch sizes with minimum programming expenditure



#### Instant Robot Programming System IRPS

You wish to weld the smallest batch sizes efficiently and automated? Particularly in steel and metal construction, the programming expenditure for automated welding of small batch sizes is often disproportionally high. Use the IRPS Instant Robot Programming System to create programs for automated welding in a short time. So the automated welding of workpieces in batch size 1 pays off now.

# **Overview of the IRPS benefits:**

### Minimum programming expenditure

- Enormous saving of time
- Increase of the system efficiency
- CAD workplace not necessary

#### Recognition of position and tolerances of the workpiece

- Excellent weld quality
- Saving of time because re-teaching is not necessary

### Reduction/Absence of the clamping device

Reduction of the investment costs

CLOOS

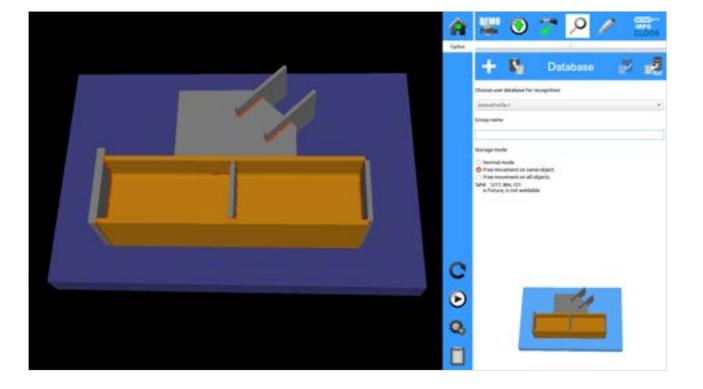
Minimisation of non-productive times

## Shortening of planning times

- Just-in-time production
- Reduced personnel and material binding
- Quick delivery periods

### Intuitive operation

- Flexible use of personnel and minimum training expenditure
- Knowledge of robot programming and welding not necessary



# That's how it works:

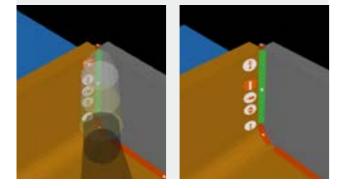
# Check and change

The IRPS has many functions available so that you can process the generated 3D data of the workpiece at the screen simply and intuitively:

- Weld length
- Weld direction
- Welding order
- Angle and distance of the torch to the weld
- Changes of the welding parameters
- Set tack points
- Insert tactile 2D search runs

CLOOS

Create paths for multi-layer welding



# Placing

The operator freely positions the tacked workpiece on the robot working station.



# 2.

**Scanning** The scanner mounted at a linear track scans the working surface of the robot system and saves the result.

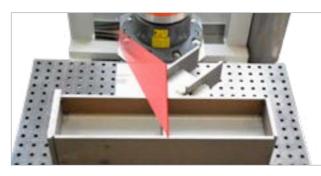
# Visualising

The IRPS converts the saved scanner data into a 3D model. From the comparison of the 3D model with the component geometry saved in the IRPS the welding program is generated automatically. Then the IRPS sends the completely generated program including all welding data to the robot controller.

# Welding

The operator starts welding via a button at the IRPS screen.







# Weld your way.



# With CLOOS you weld and cut ...

